# **ON REDUCING EFFORT IN** EVALUATING LAPAROSCOPIC SKILLS



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### ABSTRACT

Training and evaluation of laparoscopic skills have become an important aspect of young surgeons' education. The evaluation process is currently performed manually by experienced surgeons through reviewing video recordings of laparoscopic procedures for detecting technical errors using conventional video players and specific pen and paper rating schemes. The problem is, that the manual review process is time-consuming and exhausting, but nevertheless necessary to support young surgeons in their educational training. Motivated by the need to reduce the effort in evaluating laparoscopic skills, we investigate state-of-the-art content analysis approaches for finding error-prone video sections.

POSSIBLE ERRORS IN LAPAROSCOPIC SURGERY									
	ERROR CLASS								
SURGICAL ACTIVITY	Too much force/distance	Too little force/distance	Wrong orientation	Inadequate visualization					
Abdominal	An instrument tip is		An instrument tip	An instrument is out					
access	moved out of view.		hits tissue.	of view.					
Use of energy devices	A cautery instru- ment (HF) slips off.	A forceps fails to grasp tissue.	An active forceps is misplaced.	Smoke obscures the view on a forceps.					
	1985								

Tissue slips from a

forceps (left).



## A laparoscopic surgery is a complex sequence of surgical activities and human errors can occur. Such errors do not necessarily have fatal consequences, but repeated mistakes can only be avoided by recognizing them. The most frequent errors in laparoscopic Roux-en-Y gastric bypasses [1] and hysterectomies [2] occur during

- abdominal access of trocars and instruments,
- grasping and dissection,
- suturing,
- and use of energy devices.

Automatic detection of technical errors in videos of laparoscopic procedures is not a trivial task and is accompanied by many research challenges in vision-based object and action recognition:

- Large variations in appearance of objects (e.g., viewpoint, scale, occlusion, orientation, illumination, camera motion)
- Conditions (e.g., specular reflections, blurriness, smoke, blood)
- Strong object motion (i.e., errors occur in a fraction of a second)

# **OBJECTIVES AND CONTRIBUTION**

The purpose is to identify error-prone surgical activities for highlighting relevant sections in videos to reduce the surgeon's effort in evaluating laparoscopic skills. The research question is:

To what extent can visual object detection methods be used to identify error-prone surgical activities with reasonable accuracy?

We investigate surgical activities and deep learning approaches and the following research objectives will be addressed by the mentioned research question:

- 1. Evaluating instrument detection methods with a focus on high precision by investigating and improving upon state-of-the-art convolutional neural networks (CNNs).
- 2. Designing and developing a technical skill evaluation prototype to integrate applicable object detection approaches.

Grasping and Tissue wraps around a forceps. dissection











Suturing





Bleeding occurs





A clamped needle is out of view.



Suction/Irrigation device is out of view.

Use of suction Tissue is sucked in

## WORK IN PROGRESS

In [3] we present different datasets addressing specific problems in gynecologic laparoscopy; among them one is for classifying different amounts of visible surgical tools composed of ~22k sample images and categorized into four content classes:









Zero Instruments

Three Instruments

Results of baseline evaluations show promising accuracy in identifying the number of instruments within images:

GoogLeNet	Jaccard Index	Recall	Precision	Specificity	Accuracy	MCC*	F1-Value	
Zero Instruments	0.862	0.928	0.924	0.976	0.965	0.903	0.926	
One Instrument	0.673	0.790	0.819	0.944	0.907	0.743	0.804	
Two Instruments	0.631	0.763	0.785	0.921	0.878	0.69	0.773	
Three Instruments	0.770	0.898	0.844	0.946	0.934	0.827	0.870	
Weighted Average	0.730	0.842	0.841	0.946	0.920	0.787	0.841	
			*MCC = Matthews Correlation Coefficient					



Bleeding occurs af

ter transection

A clip falls down.

A needle holder slipped off. slips off.

out of view.

A grasper (right) is



Instruments get

wedged together.

Scissors puncture

uninvolved tissue

A clip is misplaced.

3. Evaluating whether technical errors are recognizable with reasonable precision by learning spatio-temporal dependencies of moving objects.

#### REFERENCES

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